# Asymptotic Behaviour of the Quadratic Knapsack Problem

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### Introduction

### Quadratic Knapsack Problem (QKP)

Standard Knapsack Problem (KP) with additional "profits"  $p_{ij}$  for every pair of selected items *i* and *j*.

$$(QKP) \max \sum_{i=1}^{n} \sum_{j=1}^{n} p_{ij} x_i x_j$$
(1)

s.t. 
$$\sum_{i=1}^{n} w_i x_i \le c$$
 (2)

$$x_i \in \{0,1\}, \quad i = 1, \dots, n$$
 (3)

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 $x_i = 1$  iff item *i* is included in the solution

surveys: Pisinger [2007], Kellerer et al. [2004] ch.12

### Introduction

#### Graph Representation

Usually, not all pairs (i, j) contribute quadratic profits. Consider graph G = (V, E) with |V| = n and |E| = m.

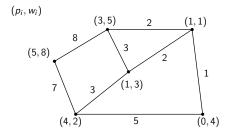
- Every vertex  $v \in V$  corresponds uniquely to an item.
- Edge  $(u, v) \in E \iff$  two items corresponding to u, v yield an additional profit, if they are both included in the solution.

$$(QKP) \max \sum_{(i,j)\in E} p_{ij} x_i x_j \tag{4}$$

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 $x_{ii} \approx$  linear profit!

# Example



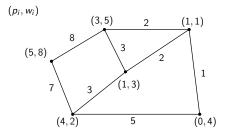
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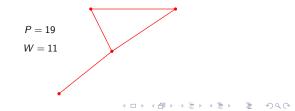
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c = 11

# Example



c = 11



# Applications and Solution Approaches

### Applications

- media mix optimization (Pferschy and Sch. [2015])
- airport and train-station location (Rhys [1970])
- VLSI-design (Ferreira et al. [1996])
- . . .

### Exact Methods

- Caprara et al. [1999]: branch and bound based on Lagrangian relaxation
- Billionnet and Soutif [2004]: Lagrangian decomposition
- Pisinger et al. [2007]: aggressive reduction strategy in order to fix some variables
- Fomeni et al. [2014]: cut and branch for sparse instances

# Solution Approaches

### (Meta)-Heuristics

- Julstrom [2015,2012]: genetic algorithm
- Fomeni and Letchford [2014]: dynamic program combined with local search
- Yang et al. [2013]: tabu search and Grasp

### All these methods perform very well!

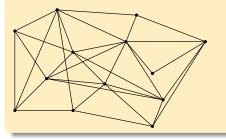
Yang et al. [2013] solve instances of up to 2000 items (gap <1.5%).

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# **Known Hardness**

- QKP is  $\mathcal{NP}$  hard because of an easy reduction from maximum clique
- No hardness results under "standard" assumptions

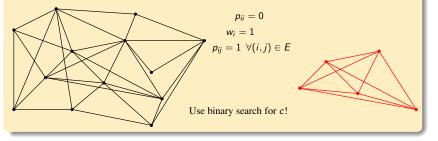
This result does not contradict the good results from above.



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# Important Connections

Densest k-subgraph (dks)

GIVEN: graph G = (V, E) and an integer k

FIND: k-vertex induced subgraph with most edges

Find the k vertex induced subgraph of a given graph G = (V, E) containing the maximum number of edges.

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It is obviously a subproblem of QKP.

# Important Connections

#### Hardness results for dks

- Feige [2002] and Khot [2006] ruled out existence of a PTAS (average case hardness assumptions)
- Alon et al. [2011] ruled out any constant factor approximation (based on hardness of random *k*-AND formulas)

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• Alon et al. [2011] showed superconstant inapproximation results (based on the hidden clique assumption)

# Consequences for QKP

### Hardness of QKP

### All these results hold for QKP

Hence the empirically observed performance of the above algorithms raises questions:

- Are these (non-standard) complexity assumptions wrong?
- Is there something wrong with the algorithms, resp. with the instances used for testing them?

We will show that the used test-instances are problematic and give a new class of hard test-instances.

# Test instances for QKP

Standard instances for QKP are randomly generated instances. This is common for many optimization problems!

Instances by Gallo et al. [1980]

- a density  $\Delta$  stands for the probability that a  $p_{ij}$  is non-zero
- whenever  $p_{ij}$  is non-zero,  $p_{ij}$  is uniformly distributed  $\in [1, 100]$
- $w_i$  is uniformly distributed  $\in [0, 50]$
- c is uniformly distributed  $\in [0, \sum w_i]$

These instances where used in all subsequent computational papers as core test instances.

# Related Results for Quadratic Objectives

#### Quadratic assignment problem

$$\min_{\phi\in S_n}\left(\sum_{i=1}^n\sum_{k=1}^n a_{ik}b_{\phi(i)\phi(k)}+\sum_{i=1}^n c_{i\phi(i)}\right)$$

- n facilities are placed to n locations
- $c_{i\phi(i)}$  is the cost of opening facility *i* at location  $\phi(i)$
- a<sub>ik</sub>b<sub>φ(i)φ(k)</sub> is the transportation cost caused by assigning facility i to φ(i) and facility k to φ(k)

Note that any feasible solution corresponds to a permutation of  $\{1, 2, ..., n\}$ .

# Related Results for Quadratic Objectives

### Asymptotic Result

Burkard and Frieze [1982] proved that:

- whenever the costs are i.i.d random variables  $\in [0,1]$
- the ratio of the optimal and worst solution tends to 1 in probability

### Generic Optimization Problems

Burkard and Frieze [1985] generalized this result to a broader class of optimization problems with quadratic objective.

They have in common that a feasible solution has a fixed number of n elements.

This does not hold for QKP - the empty knapsack is feasible.

### Prerequisites

Chernoff-Hoeffding bound by Angluin and Valiant [1979]

Let the random variables  $X_1, X_2, ..., X_n$  be independent with  $0 \le X_k \le 1$  for each k. Let  $S_n = \sum X_k$  and let  $\mu = E(S_n)$ . Then for any  $0 \le \varepsilon \le 1$ :

$$P\left[S_n \ge (1+arepsilon)\mu
ight] \le e^{-rac{1}{3}arepsilon^2\mu}$$
 $P\left[S_n \le (1-arepsilon)\mu
ight] \le e^{-rac{1}{2}arepsilon^2\mu}$ 

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# Prerequisites

#### Assumptions

- $p_{ij}$  are *i.i.d.* random variables defined on the interval [0, 1]
- weights are arbitrary numbers from [0, 1]
- the knapsack capacity c is proportional to n (i.e.  $c = \lambda n$ )

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all random variables have positive expectation (i.e.
 E(X) = μ<sub>X</sub> > 0).

# *asymptotic-QKP(n)* problem:

a-QKP(n)

a-QKP(n)  

$$\max \sum_{i=1}^{n} \sum_{j=1}^{n} P_{ij} x_i x_j \quad (5)$$
s.t. 
$$\sum_{i=1}^{n} W_i x_i \le \lambda n \quad (6)$$

$$x_i \in \{0,1\}, \quad i = 1, \dots, n \quad (7)$$

If the weights are random variables:

 ${\it L}$  denotes the maximum number of items which can be feasibly included into the knapsack

L itself is a random variable

# *asymptotic-QKP(n)* problem:

### a-QKP(n)

Let a realization of  $W_i$  be given:

Then the realization of L can be determined by ordering the items in non-decreasing order of their realized weights.

$$L \approx I$$
 such that  $\sum_{i=1}^{I} w_i \leq \lambda n$  and  $\sum_{i=1}^{I+1} w_i > \lambda n$ .

#### **Different Solutions**

- Z<sup>A</sup>(n) denotes the random variable corresponding to the objective value that results by including the L lightest items.
- Z\*(n) denotes the random variable which corresponds to the optimal solution value of the given instance.

### Main Result

For any positive constant  $\delta$  we get:

$$\lim_{n\to\infty} P\left[\frac{Z^*(n)}{Z^A(n)} \le (1+\delta)\right] = 1$$

Hence the objective value of this easy heuristic converges in probability to the optimal objective value.

#### Consequences

- Testing QKP (meta)-heuristics with randomly generated instances is definitely not a good idea.
- Testing exact QKP algorithms with randomly generated instances should be done in a very careful way.

### Sketch of Proof

#### Relax a-QKP(n)

Relax a a-QKP(n) instance I by replacing the knapsack constraint with a cardinality constraint.

 $F'_n$  denote set of all subsets of cardinality  $I(|F'_n| = \binom{n}{l} < 2^n)$ 

For a set S we define the objective value:

$$Z_I^S(n) = \sum_{i,j\in S} P_{ij}$$

Relaxed problem seeks for:

$$Z_l^{max}(n) = \max_{S \in F_n^l} Z_l^S(n) \qquad Z_l^{min}(n) = \min_{S \in F_n^l} Z_l^S(n)$$

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# Sketch of Proof

### **Crucial Observation**

In an *a*-*QKP*(*n*) instance with *n* items at least  $\lambda n$  items fit, hence  $L \ge \lambda n$ .

 $Z^*(n)$  corresponds to a solution containing  $\leq L$  items, hence there always exits a certain index  $l' \geq \lambda n$  such that the following inequality holds:

$$Z_{l'}^{max}(n) \ge Z^*(n) \ge Z^A(n) \ge Z_{l'}^{min}(n)$$
 (8)

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Sketch of Proof

By the linearity of expectation we get for all  $S \in F'_n$ :

$$E[Z_l^S(n)] = E\left[\sum_{i \in S} P_{ii} + \sum_{1 \le i < j \le n \mid i, j \in S} P_{ij}\right] \ge$$
(9)  
$$\ge l\mu_m + \frac{l(l-1)}{2}\mu_m \ge \frac{\lambda^2 n^2}{2}\mu_m$$
(10)

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# Sketch of Proof

### **Continuous Mapping**

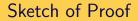
Show that for all  $l \ge \lambda n$  the following holds:

$$\lim_{n \to \infty} P\left[\frac{Z_l^{max}(n)}{Z_l^{min}(n)} \le (1+\delta)\right] = 1$$
(11)

By the continuous mapping theorem it is enough to show that:

$$\lim_{n \to \infty} P\Big[Z_l^{max}(n) \ge (1+\varepsilon)E(Q_l^n)\Big] = 0$$
(12)  
$$\lim_{n \to \infty} P\Big[Z_l^{min}(n) \le (1-\varepsilon)E(Q_l^n)\Big] = 0$$
(13)

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### Continuous Mapping

 $E(Q_l^n)$  denotes the expected objective value over all knapsacks containing *l* items, while ignoring the capacity constraint:

$$E(Q_l^n) = \sum_{S \in F_n^l} \frac{Z_l^S(n)}{\binom{n}{l}}$$
(14)

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### Sketch of Proof

Equation (12): let S' now be any set of I knapsack items.

$$P\Big[Z_{l}^{max}(n) \ge (1+\varepsilon)E(Q_{l}^{n})\Big] = P\left[\bigvee_{S\in F_{n}^{l}} \left(Z_{l}^{S}(n) \ge (1+\varepsilon)E(Q_{l}^{n})\right)\right] \le$$

$$(15)$$

$$\leq \sum_{S\in F_{n}^{l}} P\Big[Z_{l}^{S}(n) \ge (1+\varepsilon)E(Q_{l}^{n})\Big] = |F_{n}^{l}| \cdot P\Big[Z_{l}^{S'}(n) \ge (1+\varepsilon)E(Q_{l}^{n})\Big] \le$$

$$(16)$$

$$\leq |F_{n}^{l}| \cdot e^{-\frac{1}{3}\varepsilon^{2}E(Q_{l}^{n})} \le |F_{n}^{l}| \cdot e^{-\frac{1}{3}\varepsilon^{2}\frac{\lambda^{2}n^{2}}{2}\mu_{m}}$$

$$(17)$$

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# Remarks

#### Remarks

- The second inequality follows analogously.
- Almost sure convergence can be shown by applying the Borel-Cantelli-Lemma!
- The result not only covers the instances by Gallo et al. [1980], but a broad class of randomly generated instances.

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# Hidden Clique Problem

### Erdos-Renyi Random Graph

- $G(n, \frac{1}{2})$  has *n* vertices.
- each edge appears with probability  $\frac{1}{2}$
- Fact: maximum clique has size  $\approx 2 \log_2(n)$

#### Hidden Clique Problem

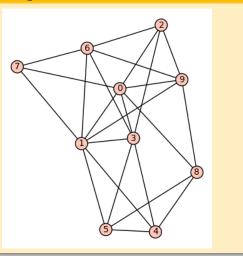
• Plant a clique of size  $l >> 2 \log_2(n)$  into  $G(n, \frac{1}{2})$ 

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• Goal: find the planted clique

# Hidden Clique Problem

### Example of a $G(10, \frac{1}{2})$



# Hidden Clique Assumption

Finding the hidden clique in polynomial time when  $l = n^c$  with  $c < \frac{1}{2}$  is impossible.

- Note that *I* is huge compared to the existing clique in  $G(n, \frac{1}{2})$ .
- The dks hardness result of Alon et al. [2011] is based on this assumption.

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# Hidden Clique Assumption

#### Hidden Clique instances

Plant a clique of size  $\lfloor n^{\frac{1}{2}} \rfloor$  into a  $G(n, \frac{1}{2})$ :

• 
$$p_{ii} = 0$$
  $w_i = 1$  and  $p_{ij} = 1$  whenever  $(i, j) \in E$ 

• 
$$c = \lfloor n^{\frac{1}{2}} \rfloor$$

• The optimal solution value of such an instance is (with overwhelming probability)

$$\frac{\lfloor n^{\frac{1}{2}} \rfloor \left( \lfloor n^{\frac{1}{2}} \rfloor - 1 \right)}{2}$$

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# **Computational Results**

For each size 10 randomly generated hidden clique instances have been tested with algorithms from the literature:

n = 200, c = 14, opt = 91			
Fomeni and Letchford [2014]	Julstrom [2005] GA	own GA	
78.9	85.4	88.3	

n = 800, c = 28, opt = 378			
Fomeni and Letchford [2014]	Julstrom [2005] GA	own GA	
298.2	325.1	356.1	

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